

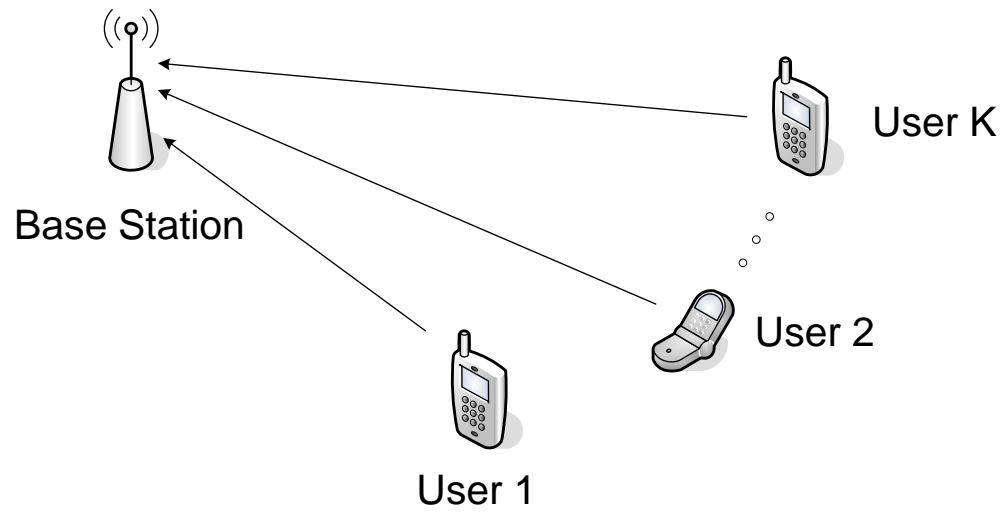
The Multiple Access Channel with Common Rate-Limited Feedback

Dor Shaviv and Yossef Steinberg
Technion—Israel Institute of Technology
ysteinbe@ee.technion.ac.il

Introduction

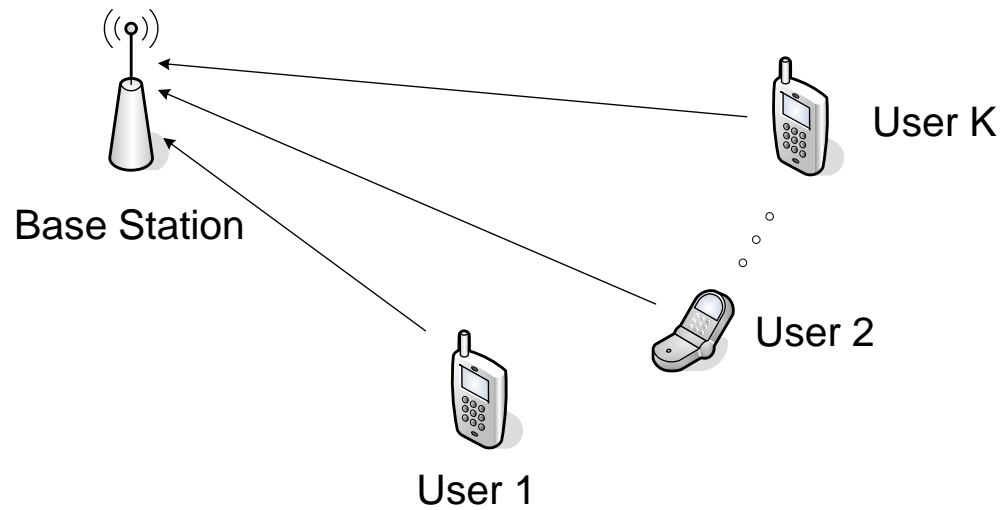
Motivation

Uplink in a Cellular Communication System



Motivation

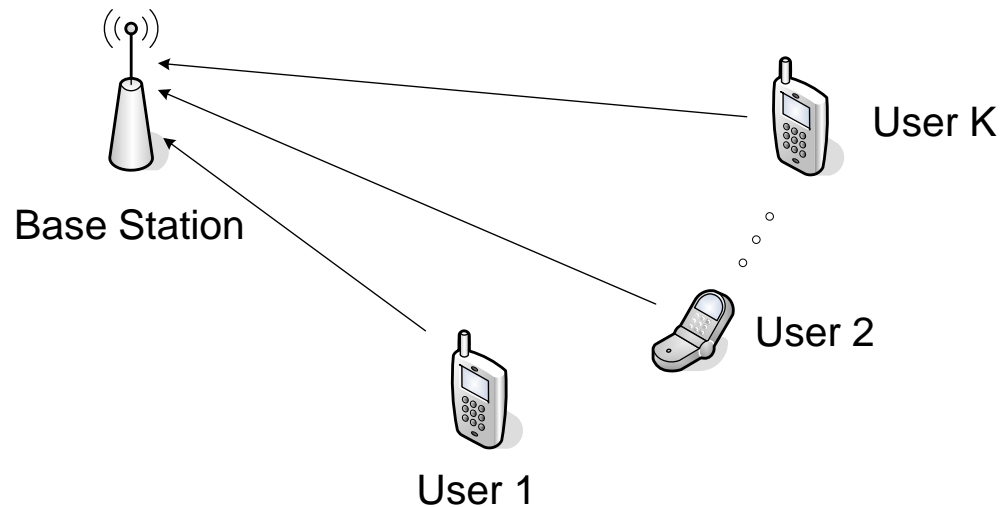
Uplink in a Cellular Communication System



- ▶ Channel depends on state (fading, multipath, interference, etc).

Motivation

Uplink in a Cellular Communication System

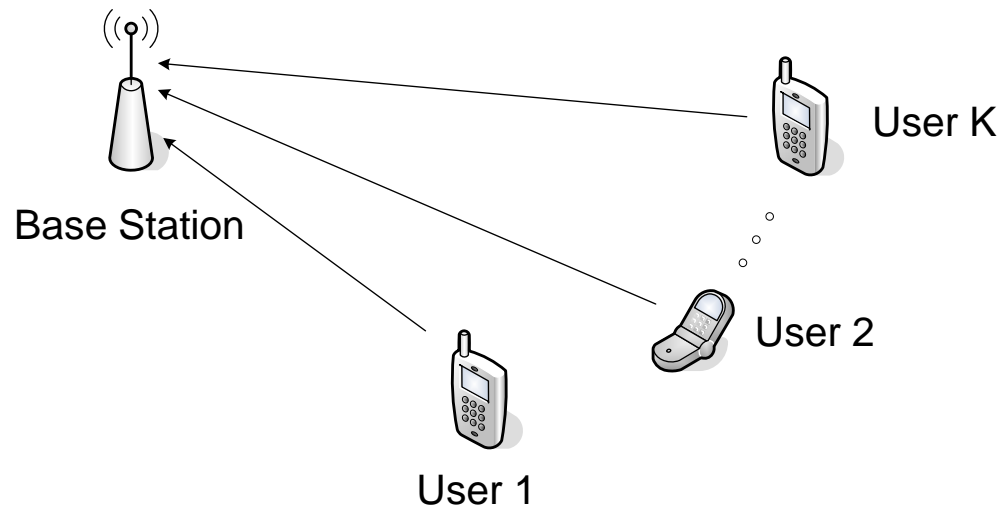


- ▶ Channel depends on state (fading, multipath, interference, etc).
- ▶ The state cannot be measured by the users. *Reflected* at the channel output (the signal available at the base station):

$$Y_i = \sum_{k=1}^K S_{k,i} X_{k,i} + \nu_i, \quad i = 1, 2, \dots$$

Motivation

Uplink in a Cellular Communication System



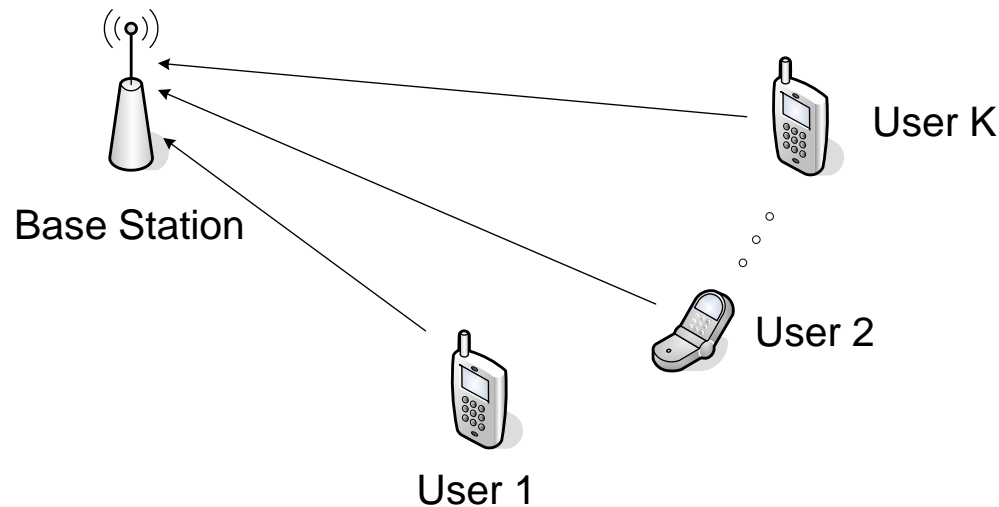
- ▶ Channel depends on state (fading, multipath, interference, etc).
- ▶ The state cannot be measured by the users. *Reflected* at the channel output (the signal available at the base station):

$$Y_i = \sum_{k=1}^K S_{k,i} X_{k,i} + \nu_i, \quad i = 1, 2, \dots$$

- ▶ Users cannot directly cooperate, or exchange information.

Motivation

Uplink in a Cellular Communication System



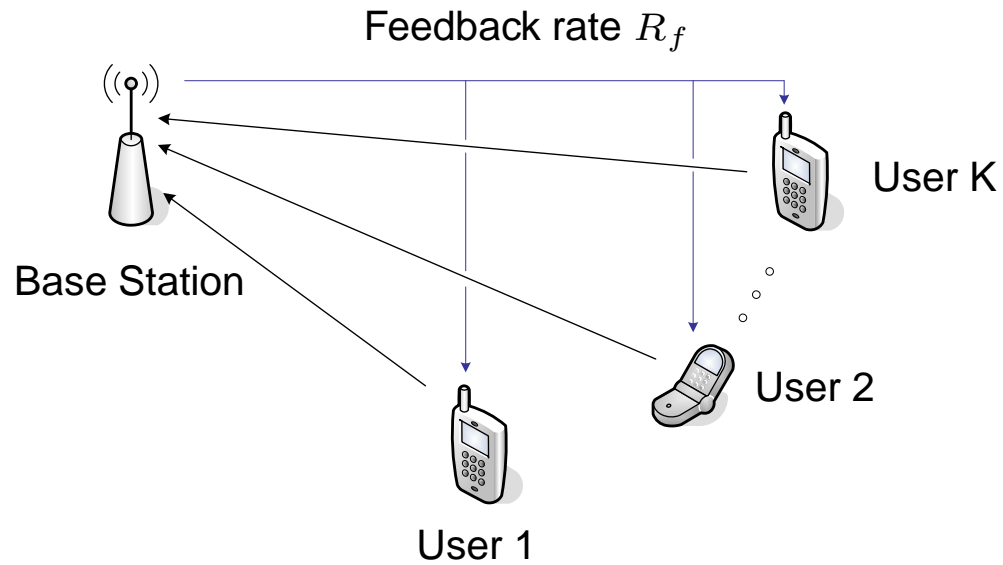
- ▶ Channel depends on state (fading, multipath, interference, etc).
- ▶ The state cannot be measured by the users. *Reflected* at the channel output (the signal available at the base station):

$$Y_i = \sum_{k=1}^K S_{k,i} X_{k,i} + \nu_i, \quad i = 1, 2, \dots$$

- ▶ Users cannot directly cooperate, or exchange information.
⇒ Use feedback from base station to the users

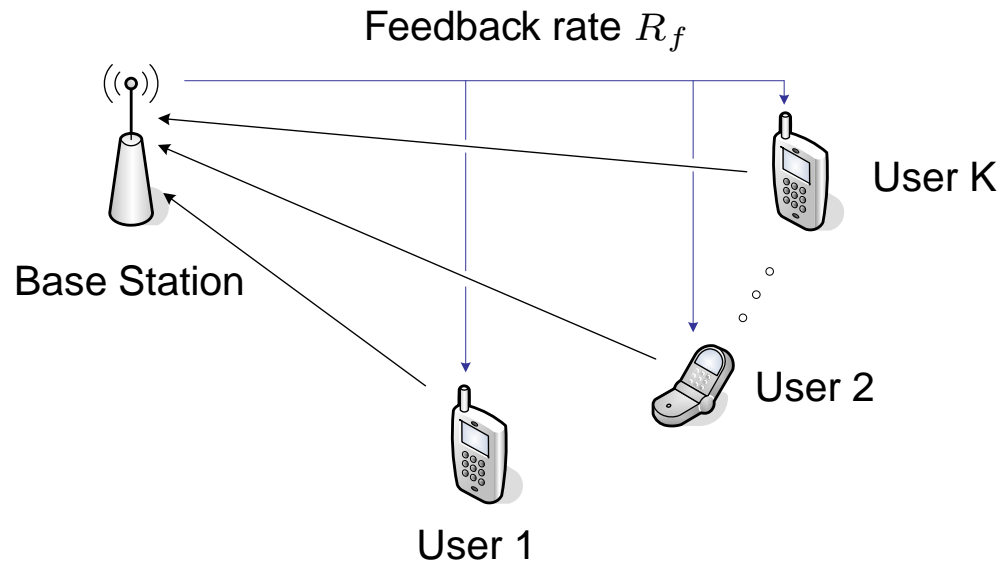
...Motivation

Uplink in a Cellular Communication System



...Motivation

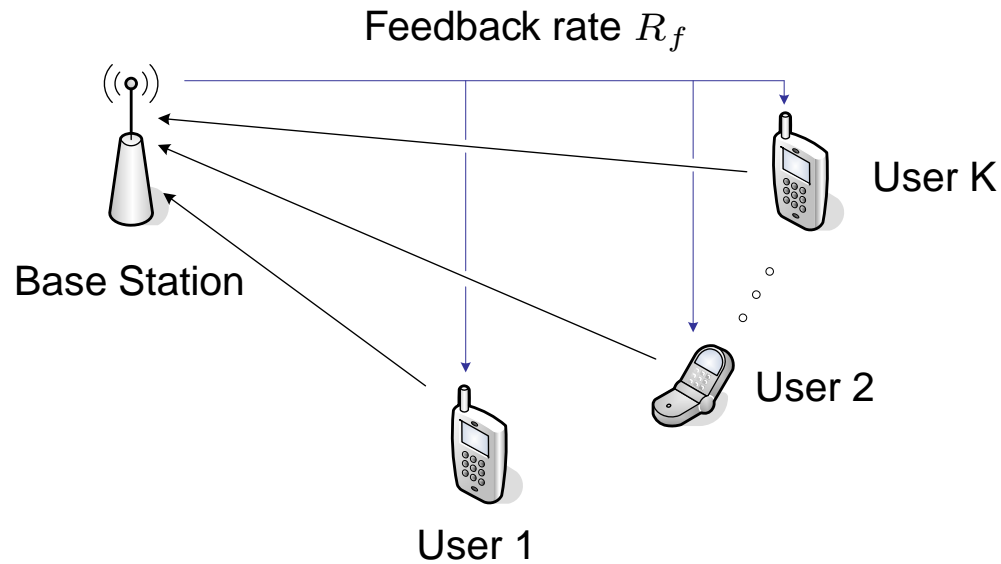
Uplink in a Cellular Communication System



In a cellular system, feedback resources are expensive. Therefore:

...Motivation

Uplink in a Cellular Communication System

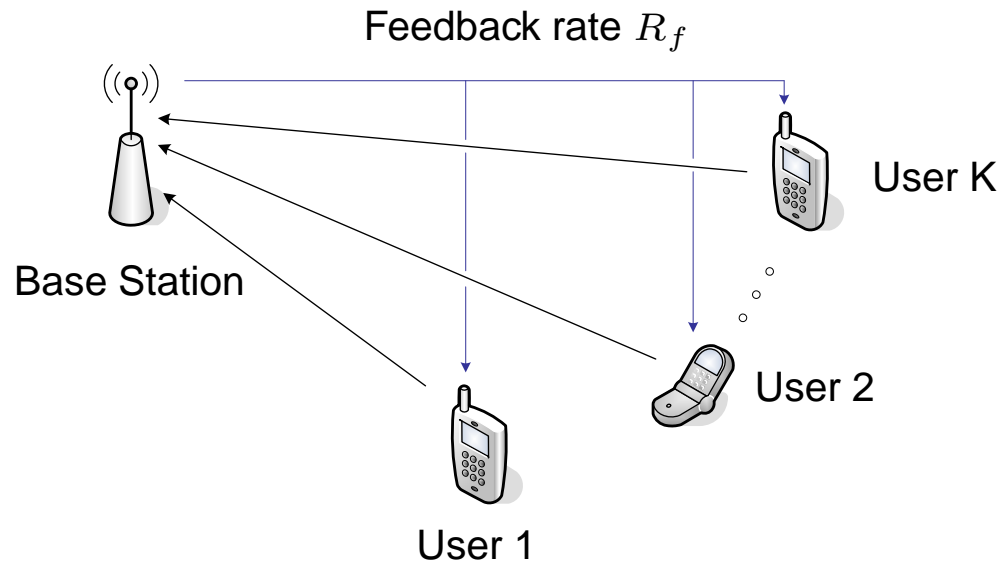


In a cellular system, feedback resources are expensive. Therefore:

- ▶ Rate limited feedback, R_f

...Motivation

Uplink in a Cellular Communication System

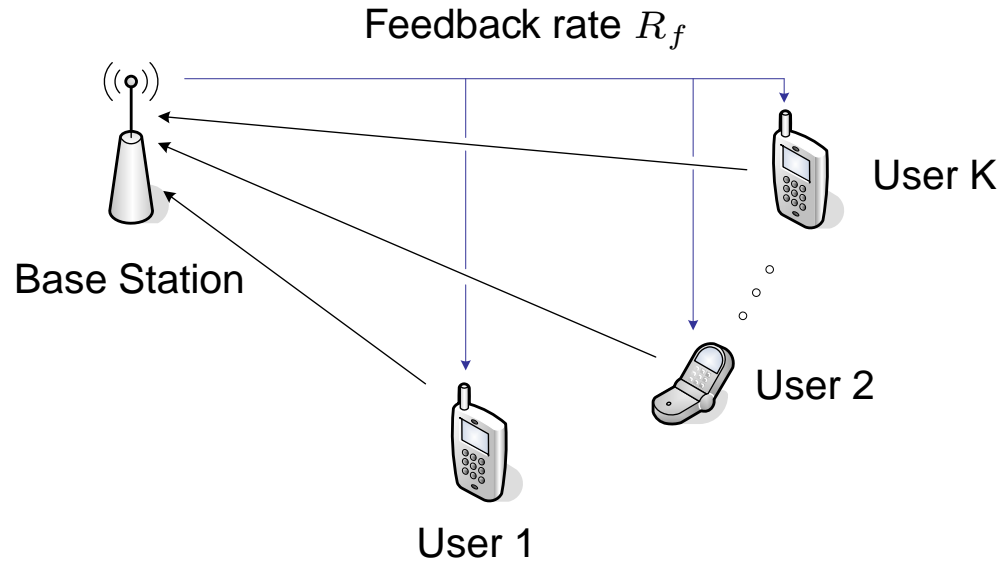


In a cellular system, feedback resources are expensive. Therefore:

- ▶ Rate limited feedback, R_f
- ▶ Common feedback link: all users get the same stream

...Motivation

Uplink in a Cellular Communication System



In a cellular system, feedback resources are expensive. Therefore:

- ▶ Rate limited feedback, R_f
- ▶ Common feedback link: all users get the same stream
- ▶ Portions of the feedback information may be dedicated

Outline

Introduction

▶ Motivation

▶ Outline

Channel and feedback models

Main result

END

- ▶ Channel and feedback models
 - ▶ Perfect feedback
 - ▶ Generalized (noisy) feedback
 - ▶ Rate-limited feedback
- ▶ Main result
- ▶ The coding scheme

Channel and feedback models

The memoryless MAC with perfect feedback

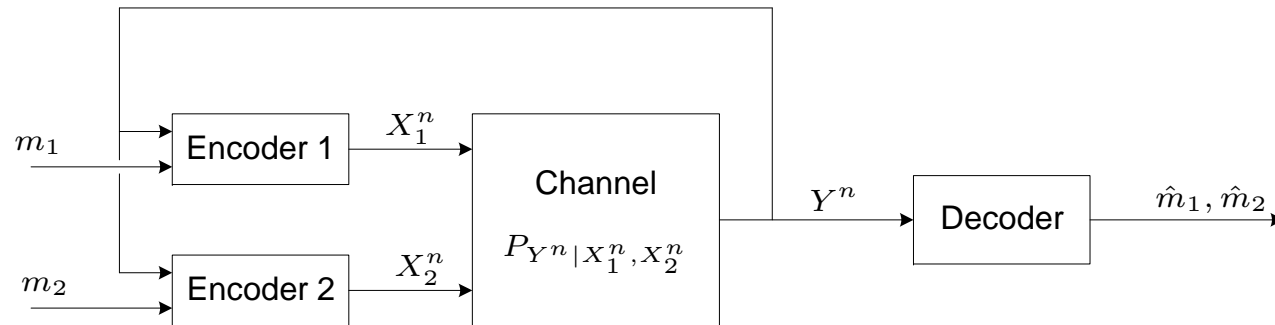
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



The memoryless MAC with perfect feedback

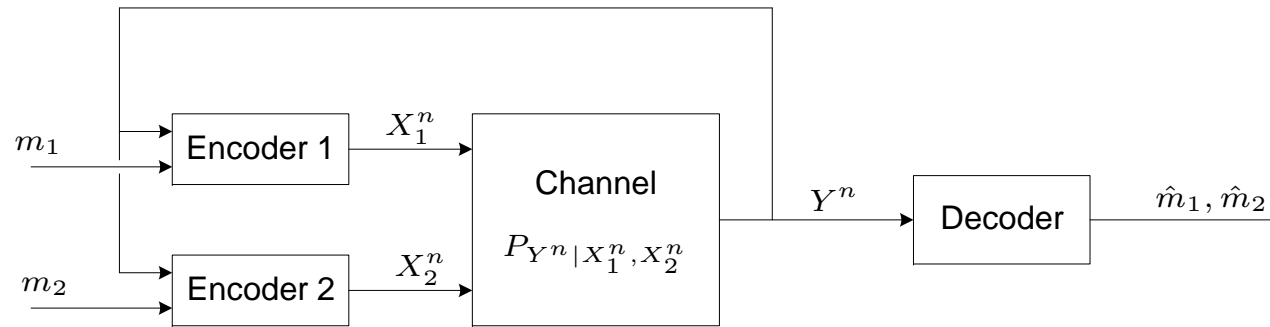
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ The channel is memoryless

$$P_{Y^n | X_1^n, X_2^n}(y^n | x_1^n, x_2^n) = \prod_{i=1}^n P_{Y | X_1, X_2}(y_i | x_{1,i}, x_{2,i})$$

The memoryless MAC with perfect feedback

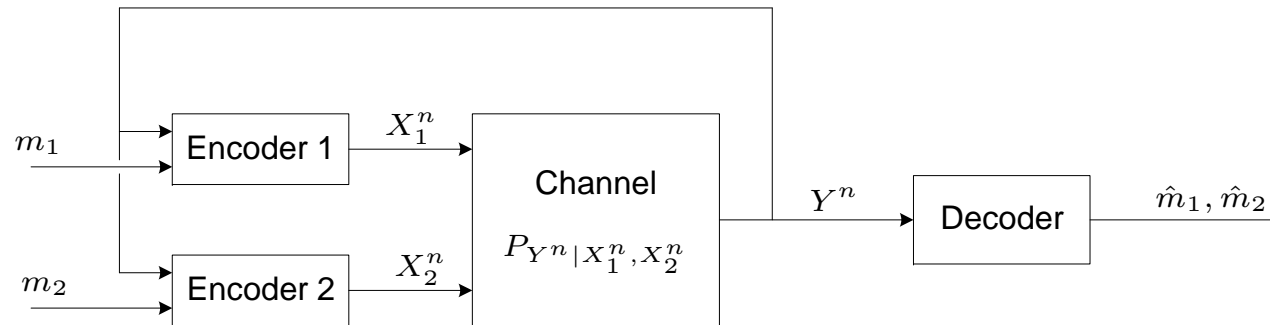
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ The channel is memoryless

$$P_{Y^n | X_1^n, X_2^n}(y^n | x_1^n, x_2^n) = \prod_{i=1}^n P_{Y | X_1, X_2}(y_i | x_{1,i}, x_{2,i})$$

- ▶ Channel encoders:

$$X_{k,i} = f_k(m_k, y_1^{i-1}), \quad k = 1, 2.$$

MAC with perfect feedback (cont'd)

Previous work

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with perfect feedback (cont'd)

Previous work

- ▶ Gaarder and Wolf 1975 – observed that feedback can increase the capacity region of memoryless MAC. The role of feedback is to establish cooperation between the users.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with perfect feedback (cont'd)

Previous work

- ▶ Gaarder and Wolf 1975 – observed that feedback can increase the capacity region of memoryless MAC. The role of feedback is to establish cooperation between the users.
- ▶ Cover and Leung 1981 – derived achievable region. Introduced superposition of information and block Markov coding, in the context of MAC.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with perfect feedback (cont'd)

Previous work

- ▶ Gaarder and Wolf 1975 – observed that feedback can increase the capacity region of memoryless MAC. The role of feedback is to establish cooperation between the users.
- ▶ Cover and Leung 1981 – derived achievable region. Introduced superposition of information and block Markov coding, in the context of MAC.
- ▶ Bross and Lapidoth 2005 – derived a new inner bound that contains the Cover-Leung region as a special case. Showed that can be strictly better than the Cover-Leung region for some channels.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with perfect feedback (cont'd)

Previous work

- ▶ Gaarder and Wolf 1975 – observed that feedback can increase the capacity region of memoryless MAC. The role of feedback is to establish cooperation between the users.
- ▶ Cover and Leung 1981 – derived achievable region. Introduced superposition of information and block Markov coding, in the context of MAC.
- ▶ Bross and Lapidoth 2005 – derived a new inner bound that contains the Cover-Leung region as a special case. Showed that can be strictly better than the Cover-Leung region for some channels.
- ▶ Ozarow 1984 – derived the capacity region of Gaussian two user MAC with perfect feedback. Used a deterministic coding scheme based on the Schalkwijk-Kailath algorithm. Ozarow's region is strictly better than the Cover-Leung region for the Gaussian MAC.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback

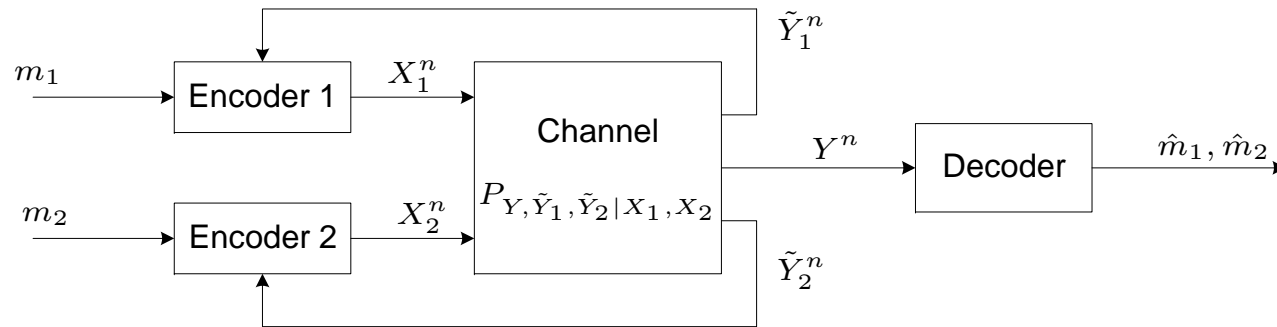
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



MAC with generalized feedback

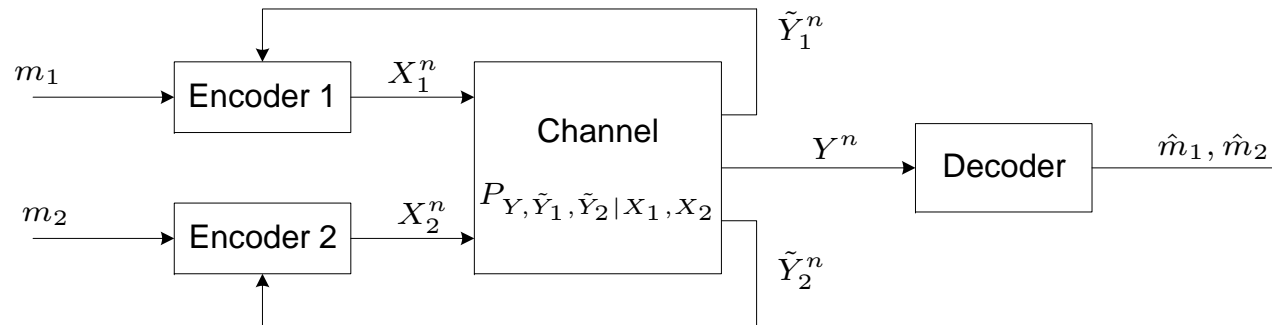
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ \tilde{Y}_1, \tilde{Y}_2 can be viewed as noisy versions of the channel output Y .

MAC with generalized feedback

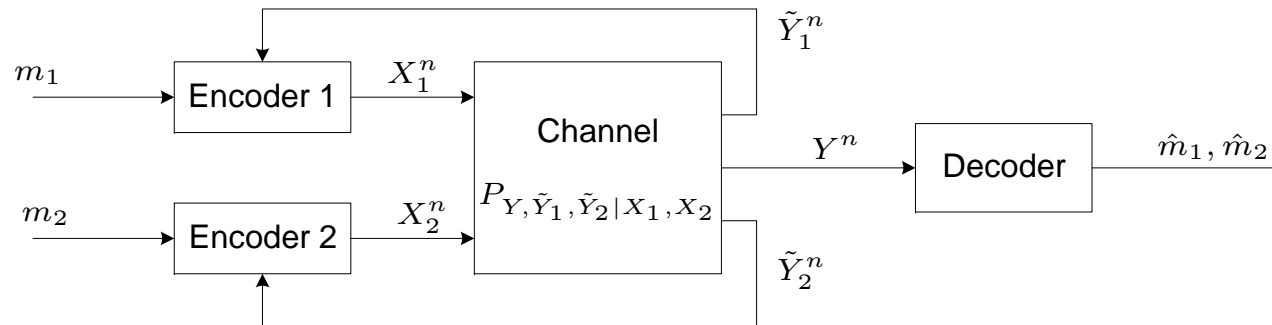
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ \tilde{Y}_1, \tilde{Y}_2 can be viewed as noisy versions of the channel output Y .
- ▶ Channel encoders:

$$X_{k,i} = f_k(m_k, \tilde{y}_{k,1}^{i-1}), \quad k = 1, 2.$$

MAC with generalized feedback (cont'd)

Previous work

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.
- ▶ Lapidoth and Wigger 2006 – studied Gaussian MAC with noisy feedback.

Suggested achievable region $\mathcal{R}_i^{(LW)}$ with the properties:

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.
- ▶ Lapidot and Wigger 2006 – studied Gaussian MAC with noisy feedback.

Suggested achievable region $\mathcal{R}_i^{(LW)}$ with the properties:

- ▶ Strictly better than \mathcal{C}_{MAC} without feedback, \forall feedback noise power

Introduction

Channel and feedback models

▶ Perfect feedback

▶ Generalized feedback

▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.
- ▶ Lapidot and Wigger 2006 – studied Gaussian MAC with noisy feedback.

Suggested achievable region $\mathcal{R}_i^{(LW)}$ with the properties:

- ▶ Strictly better than \mathcal{C}_{MAC} without feedback, \forall feedback noise power
- ▶ For feedback noise power $\rightarrow 0$, sum rate coincides with Ozarow's sum rate.

Introduction

Channel and feedback models

▶ Perfect feedback

▶ Generalized feedback

▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.
- ▶ Lapidoth and Wigger 2006 – studied Gaussian MAC with noisy feedback.

Suggested achievable region $\mathcal{R}_i^{(LW)}$ with the properties:

- ▶ Strictly better than \mathcal{C}_{MAC} without feedback, \forall feedback noise power
- ▶ For feedback noise power $\rightarrow 0$, sum rate coincides with Ozarow's sum rate.
 \implies At the limit of *almost perfect feedback*, Lapidoth-Wigger scheme provides optimal sum capacity.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.
- ▶ Lapidoth and Wigger 2006 – studied Gaussian MAC with noisy feedback.

Suggested achievable region $\mathcal{R}_i^{(LW)}$ with the properties:

- ▶ Strictly better than \mathcal{C}_{MAC} without feedback, \forall feedback noise power
- ▶ For feedback noise power $\rightarrow 0$, sum rate coincides with Ozarow's sum rate.
 \implies At the limit of *almost perfect feedback*, Lapidoth-Wigger scheme provides optimal sum capacity.
- ▶ Smooth transition from deterministic to random coding schemes.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

Previous work

- ▶ Carleial 1982 – suggested the model, and derived an achievable region.
- ▶ Lapidoth and Wigger 2006 – studied Gaussian MAC with noisy feedback.

Suggested achievable region $\mathcal{R}_i^{(LW)}$ with the properties:

- ▶ Strictly better than \mathcal{C}_{MAC} without feedback, \forall feedback noise power
- ▶ For feedback noise power $\rightarrow 0$, sum rate coincides with Ozarow's sum rate.
 \implies At the limit of *almost perfect feedback*, Lapidoth-Wigger scheme provides optimal sum capacity.
- ▶ Smooth transition from deterministic to random coding schemes.
- ▶ Gastpar and Kramer 2006 – Studied Gaussian MAC with noisy feedback. Outer bounds based on dependence-balance technique. Achievability results obtained via block coding and linear feedback.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

The model of generalized (noisy) feedback is more realistic than noiseless feedback. But it still suffers from a few shortcomings

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

The model of generalized (noisy) feedback is more realistic than noiseless feedback. But it still suffers from a few shortcomings

- ▶ The *rate of use* of the feedback link is the same as that of the main channel.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

The model of generalized (noisy) feedback is more realistic than noiseless feedback. But it still suffers from a few shortcomings

- ▶ The *rate of use* of the feedback link is the same as that of the main channel.
- ▶ Does not take into account processing (coding) at the input to the feedback link.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with generalized feedback (cont'd)

The model of generalized (noisy) feedback is more realistic than noiseless feedback. But it still suffers from a few shortcomings

- ▶ The *rate of use* of the feedback link is the same as that of the main channel.
- ▶ Does not take into account processing (coding) at the input to the feedback link.
- ▶ Hard to compare gains vs. cost of feedback.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with rate-limited feedback

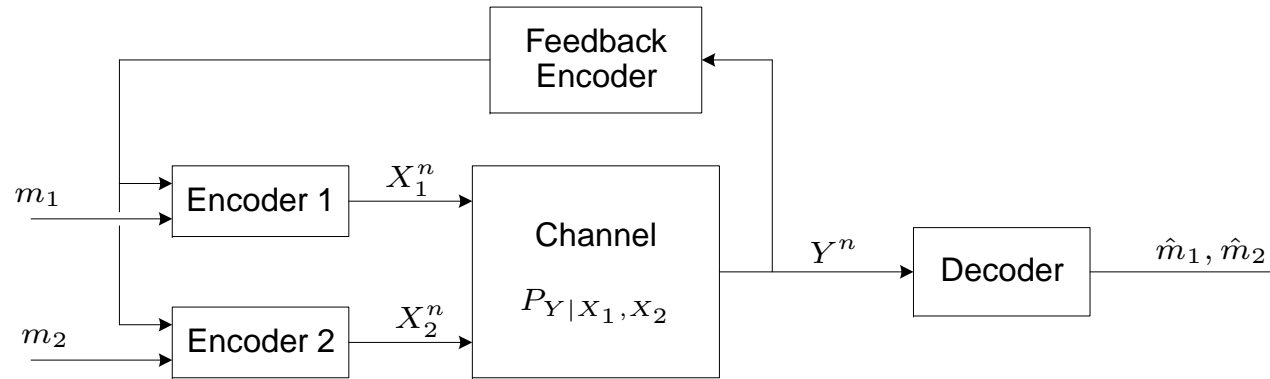
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



MAC with rate-limited feedback

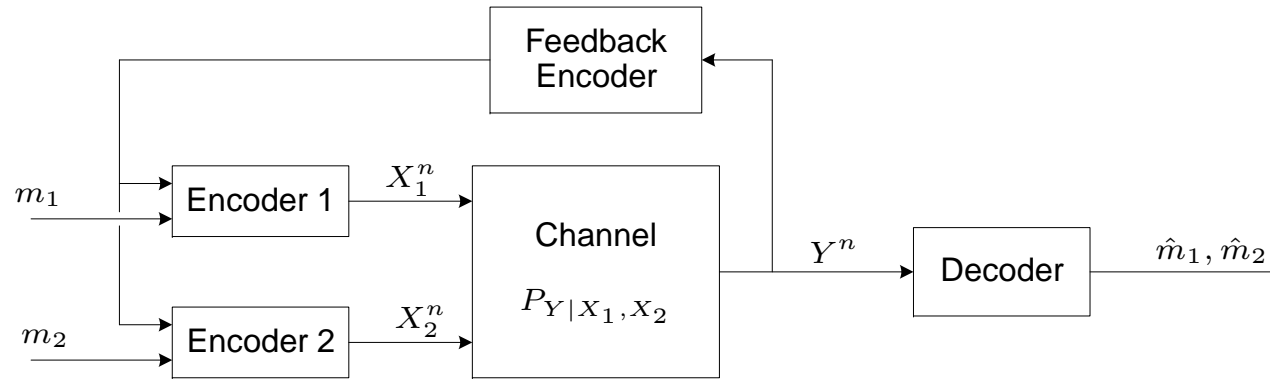
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

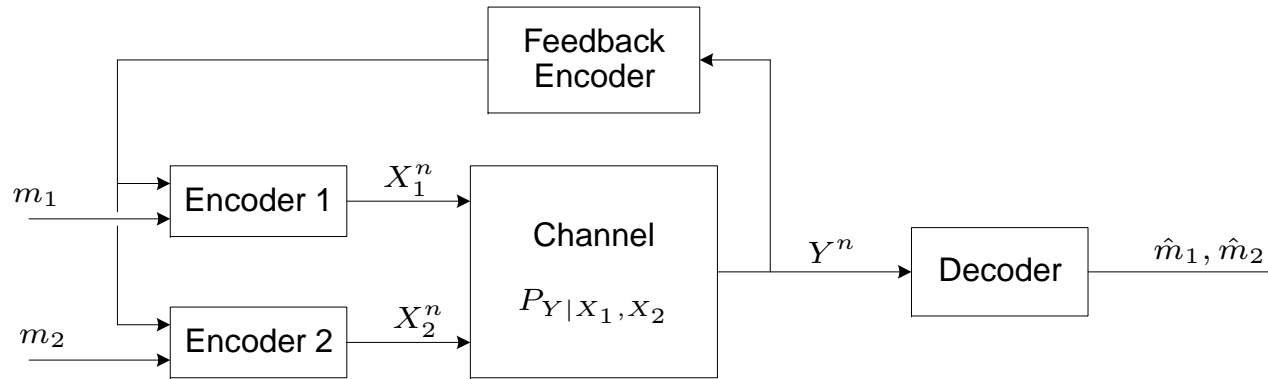
END



- ▶ Channel encoders:

$$X_{k,i} = f_k(m_k, f_0(y_1^{i-1})), \quad k = 1, 2.$$

MAC with rate-limited feedback



▶ Channel encoders:

$$X_{k,i} = f_k(m_k, f_0(y_1^{i-1})), \quad k = 1, 2.$$

How feedback rate is measured?

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with rate-limited feedback

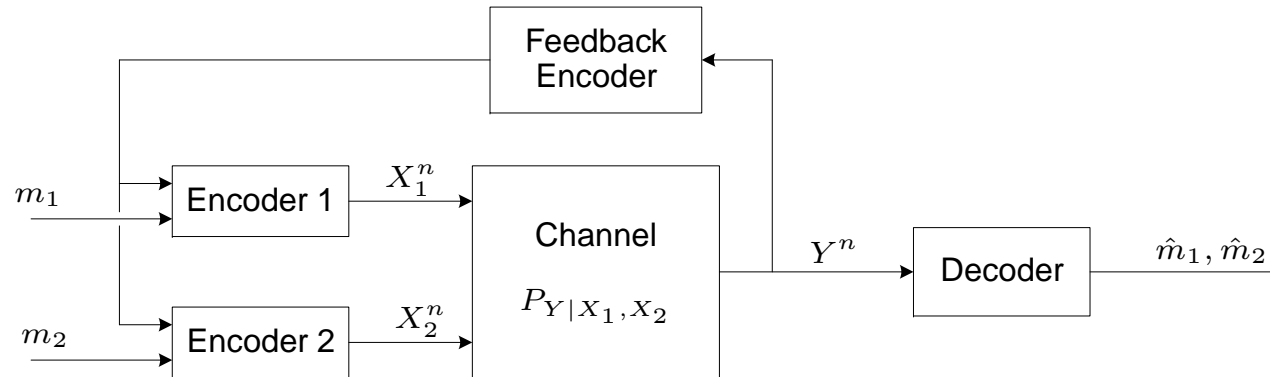
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



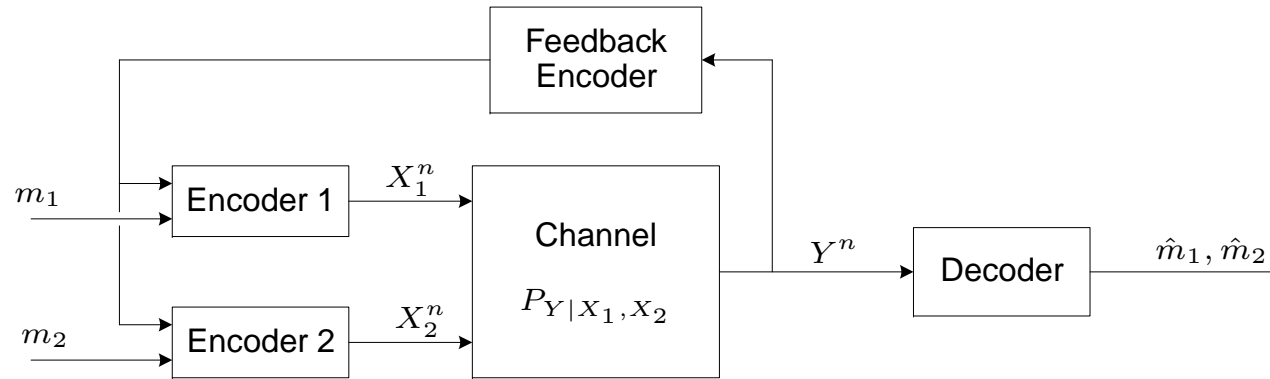
- ▶ Channel encoders:

$$X_{k,i} = f_k(m_k, f_0(y_1^{i-1})), \quad k = 1, 2.$$

How feedback rate is measured?

1. Should be more general than just one letter quantization

MAC with rate-limited feedback



▶ Channel encoders:

$$X_{k,i} = f_k(m_k, f_0(y_1^{i-1})), \quad k = 1, 2.$$

How feedback rate is measured?

1. Should be more general than just one letter quantization
2. Causal

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with rate-limited feedback (cont'd)

Introduction

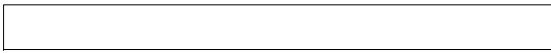
Channel and feedback models


- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback


Main result

END

m_1

X_1^n 
1 n

X_2^n 
1 n

Y^n 
1 n

MAC with rate-limited feedback (cont'd)

Introduction

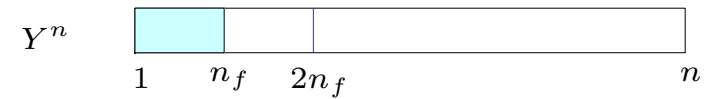
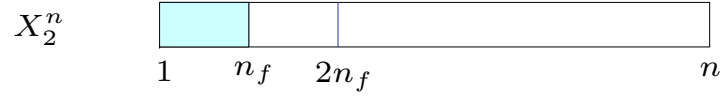
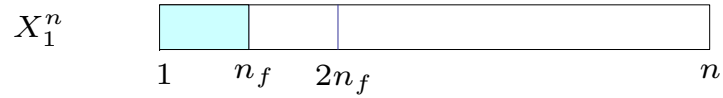
Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

m_1



MAC with rate-limited feedback (cont'd)

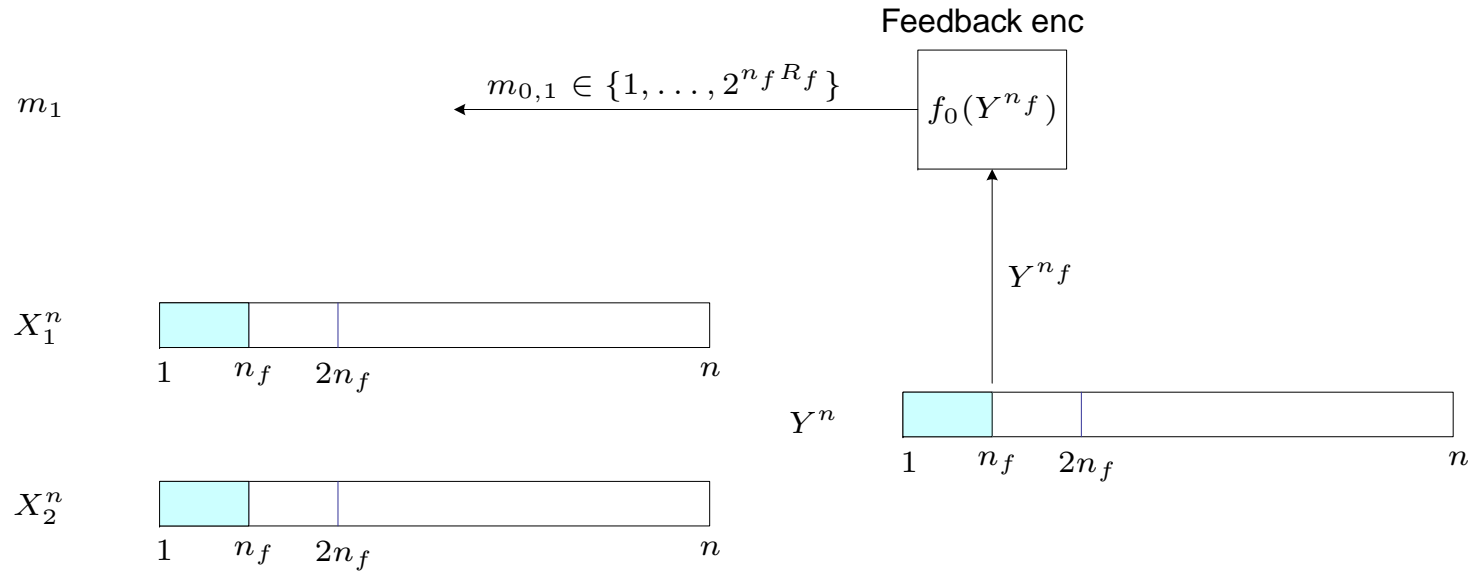
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



MAC with rate-limited feedback (cont'd)

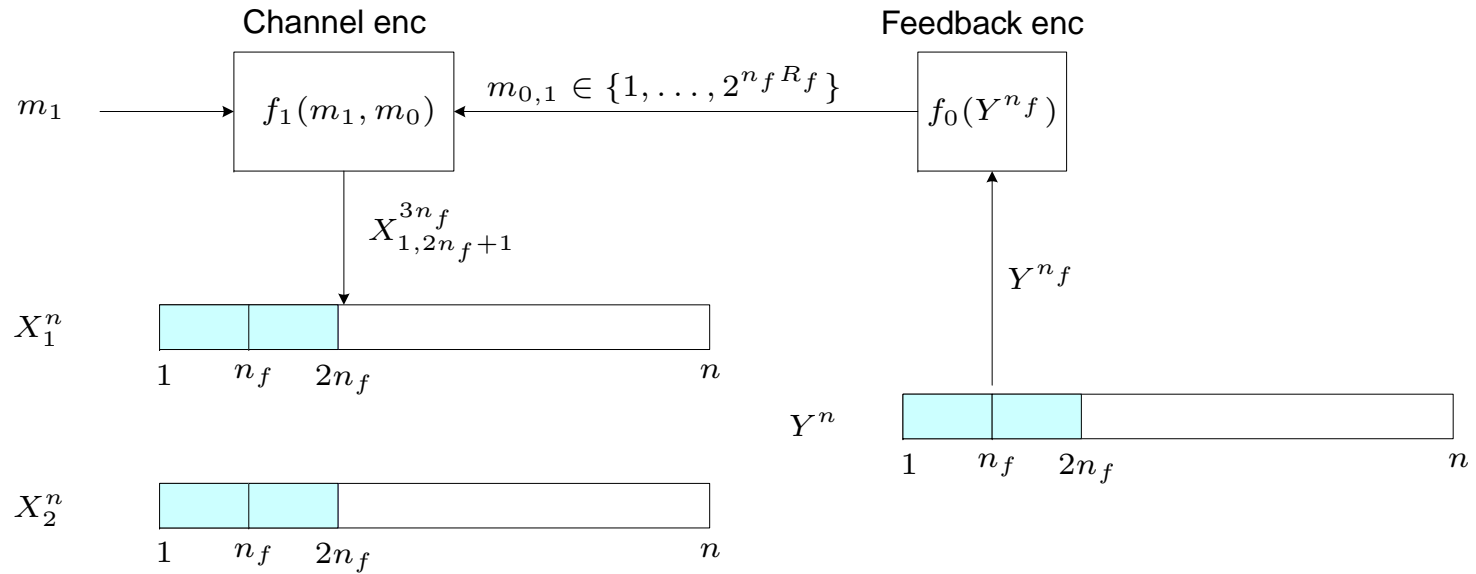
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ An inherent two sub-blocks ($2n_f$) delay.

MAC with rate-limited feedback (cont'd)

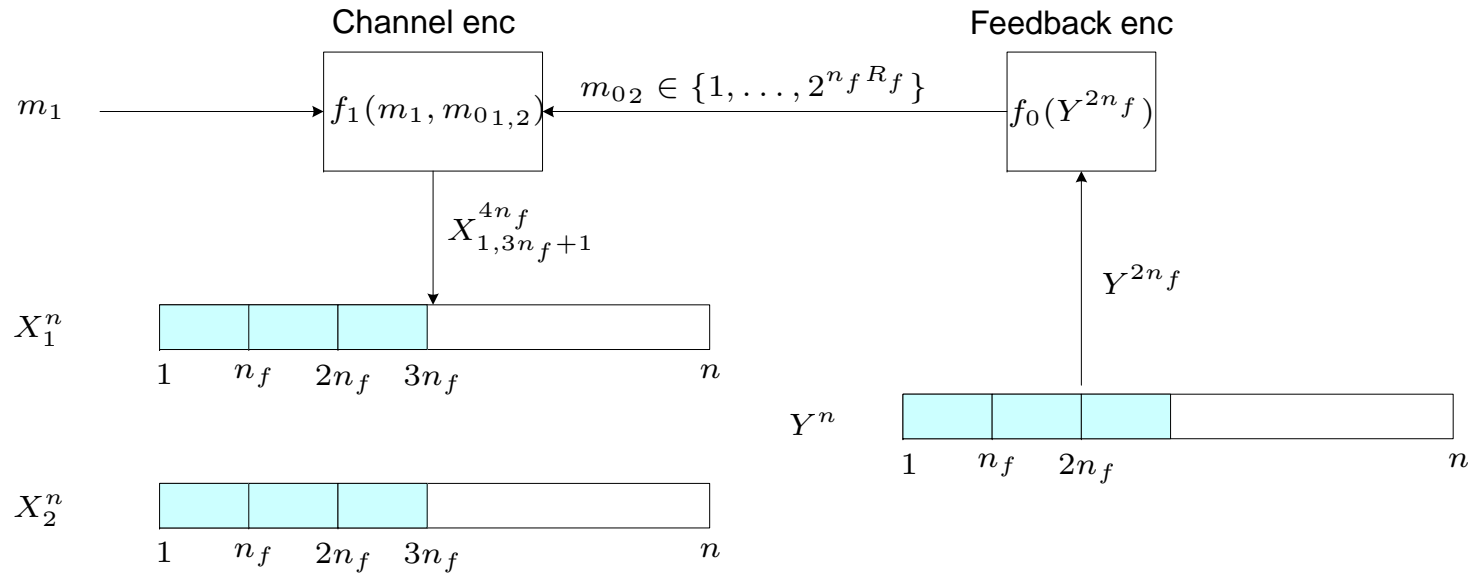
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ An inherent two sub-blocks ($2n_f$) delay.
- ▶ f_0 maps *all* the data it received thus far to one of $2^{n_f R_f}$ messages. Fixed rate feedback.

MAC with rate-limited feedback (cont'd)

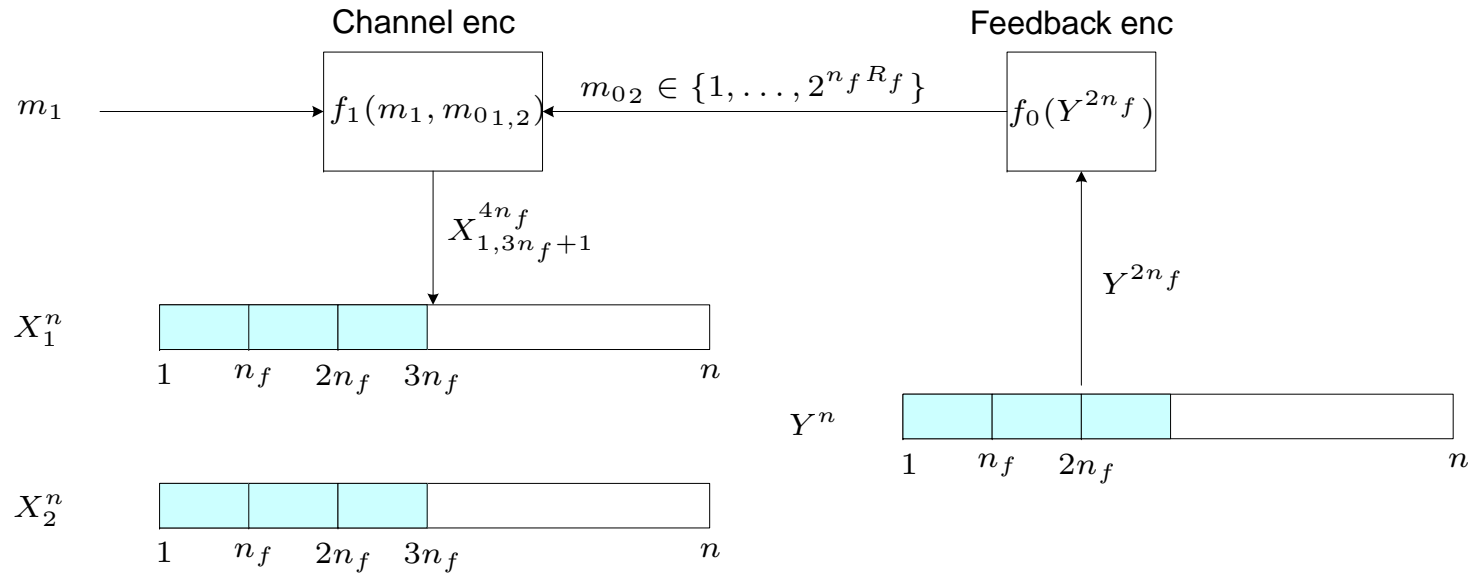
Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END



- ▶ An inherent two sub-blocks ($2n_f$) delay.
- ▶ f_0 maps *all* the data it received thus far to one of $2^{n_f R_f}$ messages. Fixed rate feedback.
- ▶ The channel encoder maps m_1 and *all* the feedback messages ($m_{0,1}, m_{0,2}, \dots$) to the next input sub-block.

MAC with rate-limited feedback (cont'd)

Choose $n, n_f < n$. $L = \lfloor n/n_f \rfloor$. Define sets of messages

$$\mathcal{M}_k = \{1, \dots, 2^{nR_k}\}, \quad k = 1, 2, \quad \mathcal{M}_0 = \{1, \dots, 2^{n_f R_f}\}.$$

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

MAC with rate-limited feedback (cont'd)

Choose $n, n_f < n$. $L = \lfloor n/n_f \rfloor$. Define sets of messages

$$\mathcal{M}_k = \{1, \dots, 2^{nR_k}\}, \quad k = 1, 2, \quad \mathcal{M}_0 = \{1, \dots, 2^{n_f R_f}\}.$$

Definition: An $(R_1, R_2, n, n_f, R_f, \epsilon)$ code for a MAC with common fixed rate feedback of rate R_f , consists of encoding functions

$$\begin{aligned} f_{1,\ell} : \quad & \mathcal{M}_1 \times \mathcal{M}_0^{[\ell-2]_+} \rightarrow \mathcal{X}_1^{n_f}, \\ f_{2,\ell} : \quad & \mathcal{M}_2 \times \mathcal{M}_0^{[\ell-2]_+} \rightarrow \mathcal{X}_2^{n_f}, \quad \ell = 1, 2, \dots, L, \end{aligned}$$

feedback encoding functions

$$f_{0,\ell} : \mathcal{Y}^{\ell n_f} \rightarrow \mathcal{M}_0, \quad \ell = 1, 2, \dots, L-2,$$

and a decoding function

$$g : \mathcal{Y}^n \rightarrow \mathcal{M}_1 \times \mathcal{M}_2,$$

with probability of error not exceeding ϵ

$$2^{-n(R_1+R_2)} \sum_{(m_1, m_2) \in \mathcal{M}_1 \times \mathcal{M}_2} P_e(m_1, m_2) \leq \epsilon,$$

Introduction

Channel and feedback models

▶ Perfect feedback

▶ Generalized feedback

▶ Rate-limited feedback

Main result

END

MAC with rate-limited feedback (cont'd)

$P_e(m_1, m_2)$ – probability of error when the pair m_1, m_2 was sent

$$P_e(m_1, m_2) = \sum_{y^n: g(y^n) \neq (m_1, m_2)} P(y^n | \mathbf{f}_1(m_1, \mathbf{f}_0), \mathbf{f}_2(m_2, \mathbf{f}_0)).$$

$\mathbf{f}_0, \mathbf{f}_1, \mathbf{f}_2$ – feedback encoder and two transmitter encoders:

$$\begin{aligned} \mathbf{f}_0 &= \mathbf{f}_0(y^n) = [m_{0,1}, m_{0,2}, \dots, m_{0,L-1}] \\ &= \left[f_{0,1}(y^{nf}), f_{0,2}(y^{2nf}), \dots, f_{0,L-1}(y^{(L-1)nf}) \right]. \end{aligned}$$

$$\begin{aligned} x_1^n &= \mathbf{f}_1(m_1, \mathbf{f}_0(y^n)) = \\ &= [f_{1,1}(m_1), f_{1,2}(m_1), f_{1,3}(m_1, f_{0,1}(y^{nf})), \dots, \\ &= f_{1,\ell}(m_1, f_{0,\ell-2}(y^{(\ell-2)nf}), \dots)]. \end{aligned}$$

Introduction

Channel and feedback models

▶ Perfect feedback

▶ Generalized feedback

▶ Rate-limited feedback

Main result

END

MAC with rate-limited feedback (cont'd)

A triple (R_1, R_2, R_f) is *achievable* for the MAC with common fixed rate feedback, if for any $\epsilon > 0$ and sufficiently large n , there exist a feedback block length n_f and an $(R_1 - \epsilon, R_2 - \epsilon, n, n_f, R_f + \epsilon, \epsilon)$ code for this channel.

Introduction

Channel and feedback models

- ▶ Perfect feedback
- ▶ Generalized feedback
- ▶ Rate-limited feedback

Main result

END

Main result

Coding scheme

Introduction

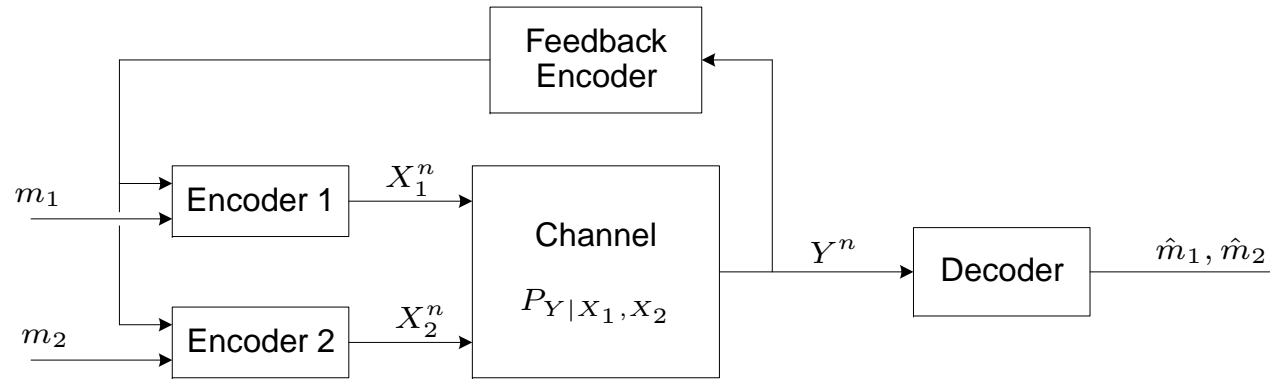
Channel and feedback models

Main result

▶ Coding scheme

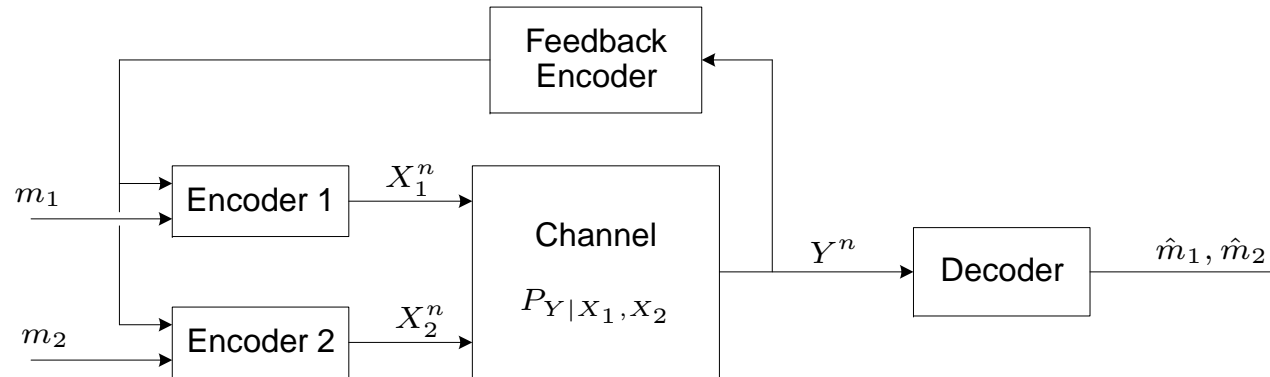
▶ Achievable region

END



Ingredients of coding scheme:

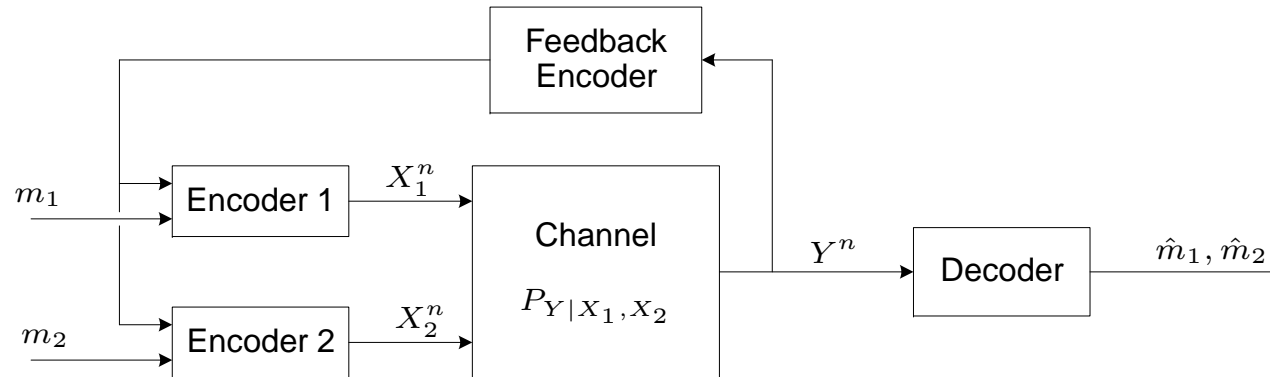
Coding scheme



Ingredients of coding scheme:

- ▶ Source coding with various levels of side information (Heegard and Berger, 1985)

Coding scheme



Ingredients of coding scheme:

- ▶ Source coding with various levels of side information (Heegard and Berger, 1985)
- ▶ Splitting the transmission rate: $R_1 = R'_1 + (R_1 - R'_1)$. R'_1 can be decoded by user 2 via the feedback.

Similarly for user 2 (Carleial 1981)

Introduction

Channel and feedback models

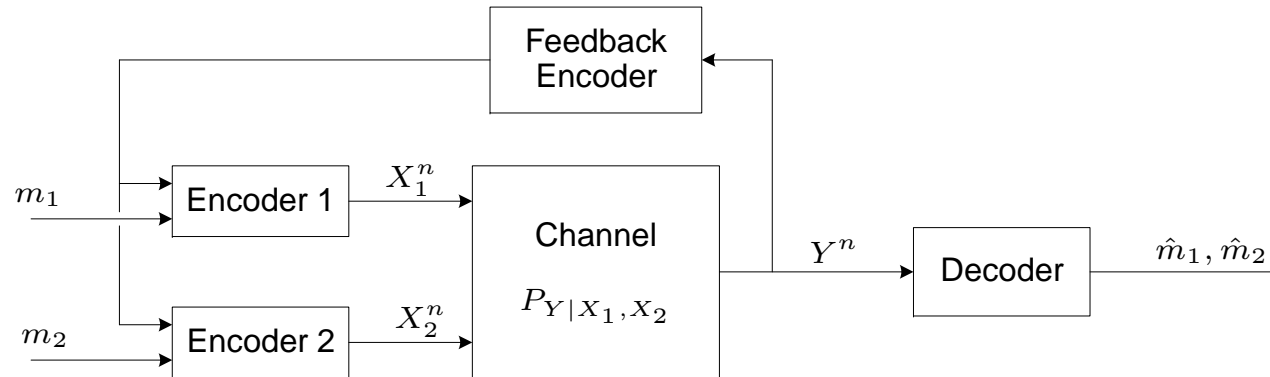
Main result

▶ Coding scheme

▶ Achievable region

END

Coding scheme



Ingredients of coding scheme:

- ▶ Source coding with various levels of side information (Heegard and Berger, 1985)
- ▶ Splitting the transmission rate: $R_1 = R'_1 + (R_1 - R'_1)$. R'_1 can be decoded by user 2 via the feedback.
Similarly for user 2 (Carleial 1981)
- ▶ Super position of information and block Markov coding (Cover and Leung 1981, Carleial 1982)

Coding scheme (cont'd)

The following structure is a special case of the general definition:

Introduction

Channel and feedback models

Main result

- ▶ Coding scheme
- ▶ Achievable region

END

Coding scheme (cont'd)

The following structure is a special case of the general definition:

- ▶ Transmission extends over $B + 2$ blocks of size n . B pairs of messages (m_1, m_2) are decoded, $m_1 \in 2^{nR_1}$, $m_2 \in 2^{nR_2}$.

Introduction

Channel and feedback models

Main result

- ▶ Coding scheme
- ▶ Achievable region

END

Coding scheme (cont'd)

The following structure is a special case of the general definition:

- ▶ Transmission extends over $B + 2$ blocks of size n . B pairs of messages (m_1, m_2) are decoded, $m_1 \in 2^{nR_1}$, $m_2 \in 2^{nR_2}$.
- ▶ At each block b , m_1 is represented by two indices:

$$j_1 \in 2^{nR'_1}, \quad k_2 \in 2^{n(R_1 - R'_1)}.$$

Similarly for m_2 (indices j_2, k_2). The pairs (j_1, j_2) are partitioned into *bins*.

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Coding scheme (cont'd)

The following structure is a special case of the general definition:

- ▶ Transmission extends over $B + 2$ blocks of size n . B pairs of messages (m_1, m_2) are decoded, $m_1 \in 2^{nR_1}$, $m_2 \in 2^{nR_2}$.
- ▶ At each block b , m_1 is represented by two indices:

$$j_1 \in 2^{nR'_1}, \quad k_2 \in 2^{n(R_1 - R'_1)}.$$

Similarly for m_2 (indices j_2, k_2). The pairs (j_1, j_2) are partitioned into *bins*.

- ▶ R_f, R'_1, R'_2 , and the feedback coding are designed so that user 1 knows $j_{2,b-2}$, and user 2 knows $j_{1,b-2}$ at end of block b .

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Coding scheme (cont'd)

The following structure is a special case of the general definition:

- ▶ Transmission extends over $B + 2$ blocks of size n . B pairs of messages (m_1, m_2) are decoded, $m_1 \in 2^{nR_1}$, $m_2 \in 2^{nR_2}$.
- ▶ At each block b , m_1 is represented by two indices:

$$j_1 \in 2^{nR'_1}, \quad k_2 \in 2^{n(R_1 - R'_1)}.$$

Similarly for m_2 (indices j_2, k_2). The pairs (j_1, j_2) are partitioned into *bins*.

- ▶ R_f, R'_1, R'_2 , and the feedback coding are designed so that user 1 knows $j_{2,b-2}$, and user 2 knows $j_{1,b-2}$ at end of block b .
- ▶ Thus at the start of block b , each user knows i_b , the *bin number* of the pair $(j_{1,b-2}, j_{2,b-2})$.

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Coding scheme (cont'd)

The following structure is a special case of the general definition:

- ▶ Transmission extends over $B + 2$ blocks of size n . B pairs of messages (m_1, m_2) are decoded, $m_1 \in 2^{nR_1}$, $m_2 \in 2^{nR_2}$.
- ▶ At each block b , m_1 is represented by two indices:

$$j_1 \in 2^{nR'_1}, \quad k_2 \in 2^{n(R_1 - R'_1)}.$$

Similarly for m_2 (indices j_2, k_2). The pairs (j_1, j_2) are partitioned into *bins*.

- ▶ R_f, R'_1, R'_2 , and the feedback coding are designed so that user 1 knows $j_{2,b-2}$, and user 2 knows $j_{1,b-2}$ at end of block b .
- ▶ Thus at the start of block b , each user knows i_b , the *bin number* of the pair $(j_{1,b-2}, j_{2,b-2})$.
- ▶ i_b is sent *coherently* by the two users to the decoder, reducing its uncertainty about the message at block $b - 2$.

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Coding scheme (cont'd)

The following structure is a special case of the general definition:

- ▶ Transmission extends over $B + 2$ blocks of size n . B pairs of messages (m_1, m_2) are decoded, $m_1 \in 2^{nR_1}$, $m_2 \in 2^{nR_2}$.
- ▶ At each block b , m_1 is represented by two indices:

$$j_1 \in 2^{nR'_1}, \quad k_2 \in 2^{n(R_1 - R'_1)}.$$

Similarly for m_2 (indices j_2, k_2). The pairs (j_1, j_2) are partitioned into *bins*.

- ▶ R_f, R'_1, R'_2 , and the feedback coding are designed so that user 1 knows $j_{2,b-2}$, and user 2 knows $j_{1,b-2}$ at end of block b .
- ▶ Thus at the start of block b , each user knows i_b , the *bin number* of the pair $(j_{1,b-2}, j_{2,b-2})$.
- ▶ i_b is sent *coherently* by the two users to the decoder, reducing its uncertainty about the message at block $b - 2$.

The new ingredient relative to Carleial is the feedback coding

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Coding scheme (cont'd)

Introduction

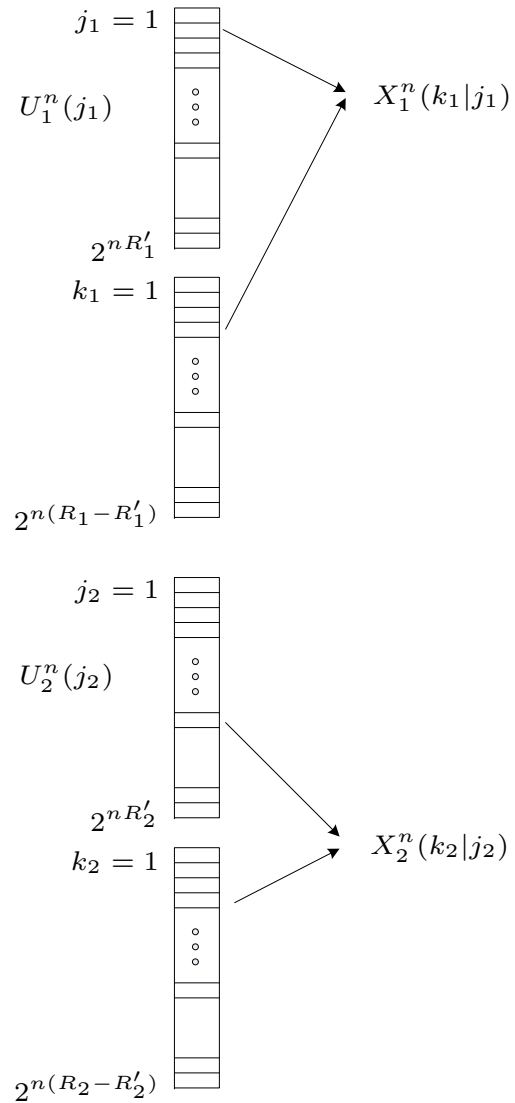
Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END



Coding scheme (cont'd)

Introduction

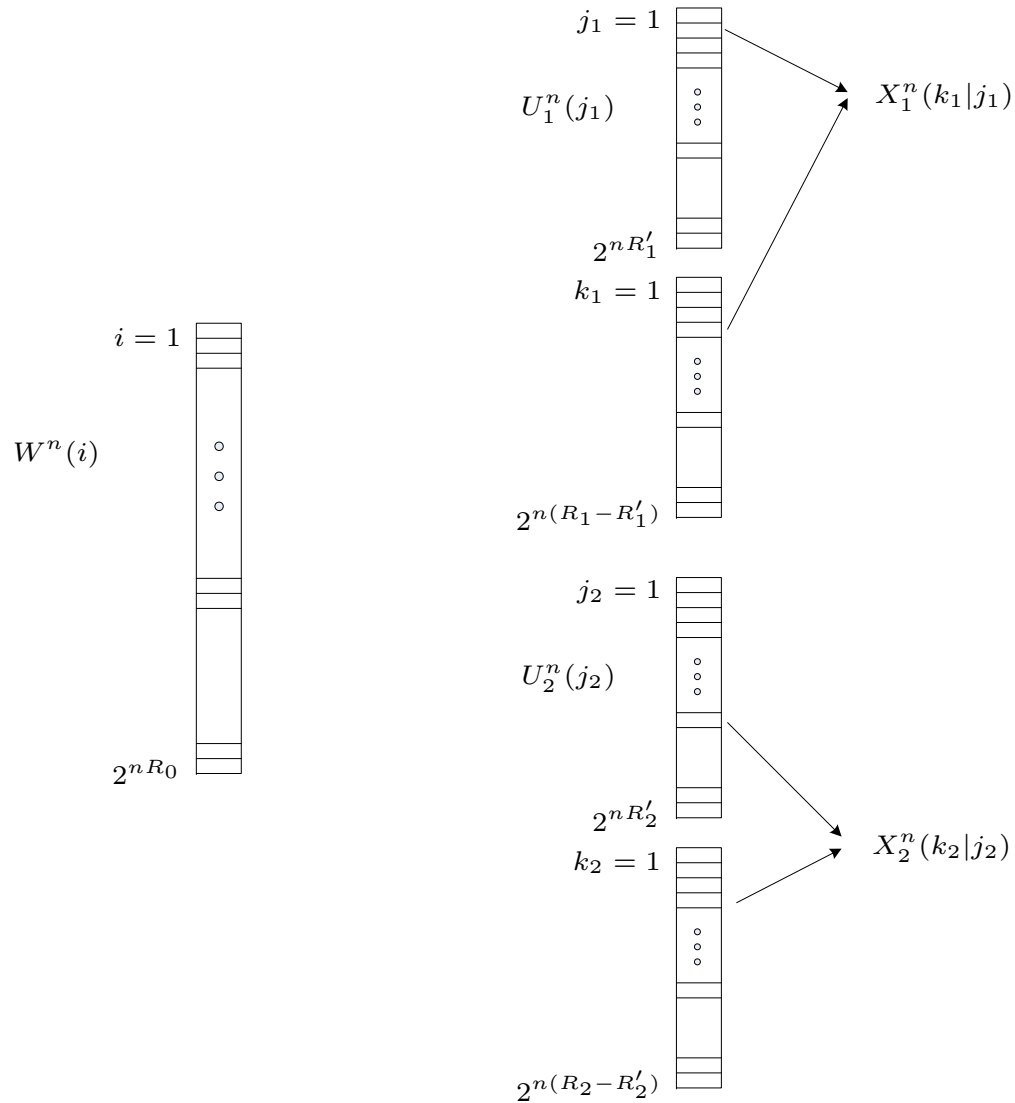
Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END



Coding scheme (cont'd)

Introduction

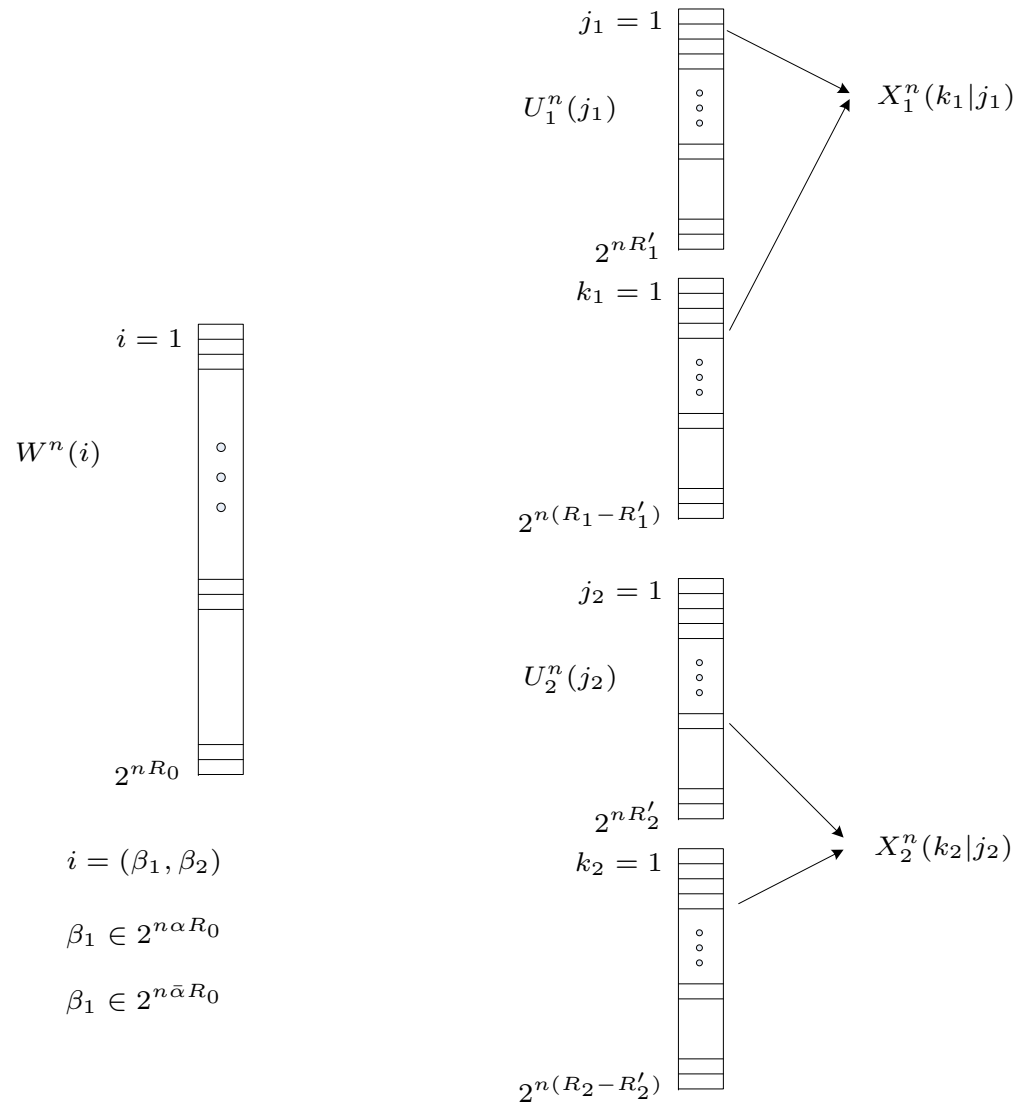
Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END



Coding scheme (cont'd)

Introduction

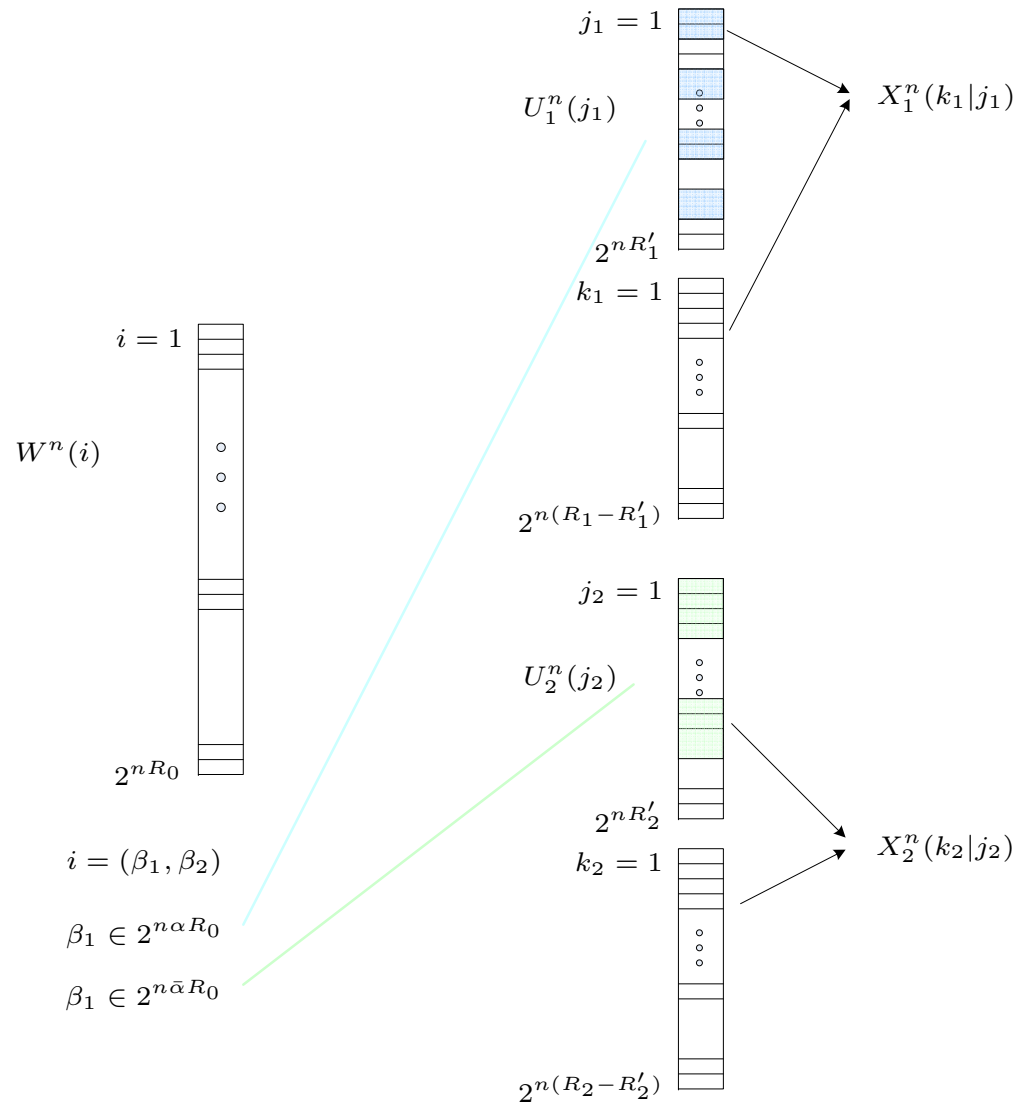
Channel and feedback models

Main result

► Coding scheme

► Achievable region

END



Coding scheme (cont'd)

Introduction

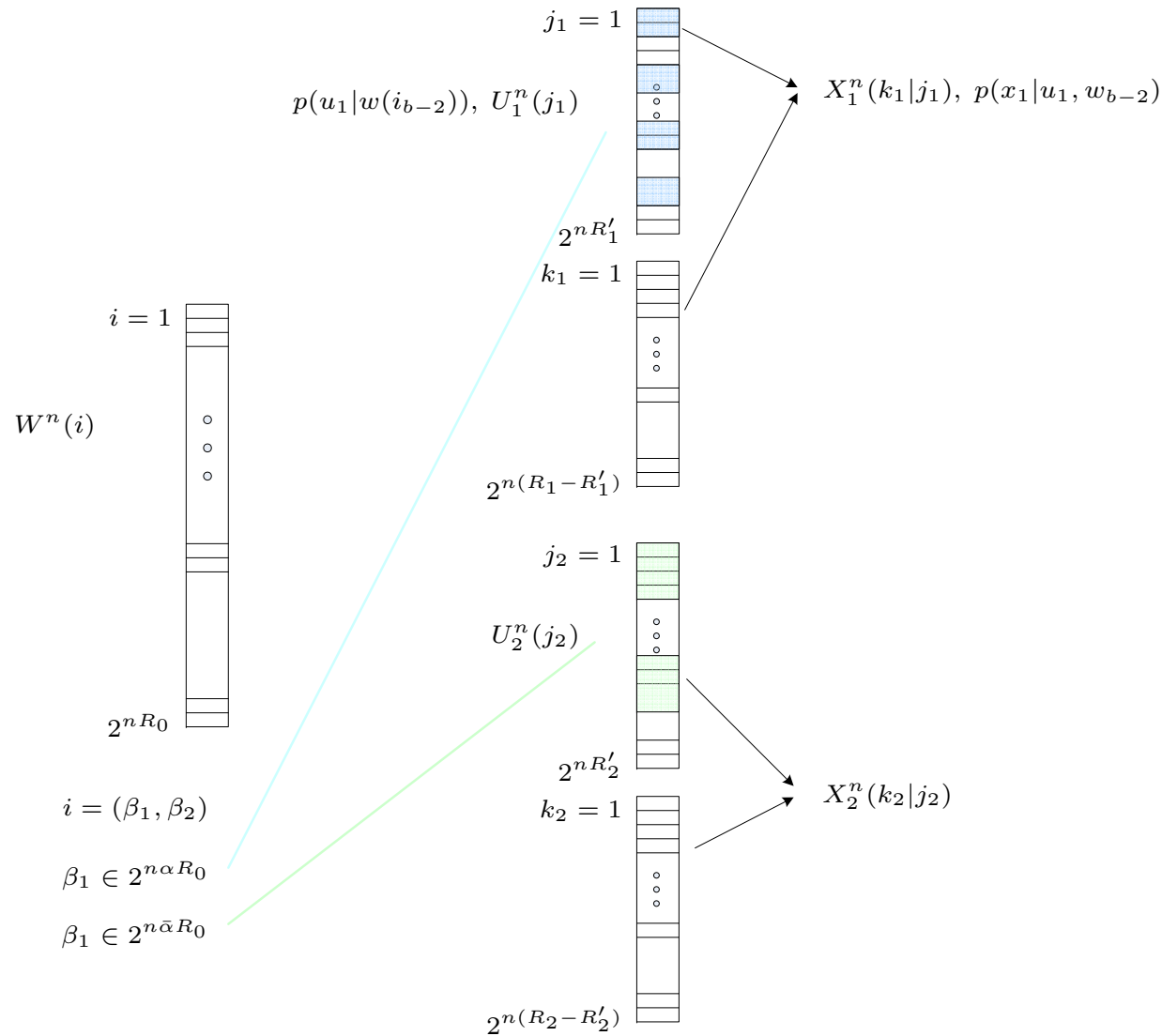
Channel and feedback models

Main result

► Coding scheme

► Achievable region

END



Achievable region

Definition: Let \mathcal{R}_i be the set of all (R_1, R_2, R_f) for which there exist $0 \leq R'_1 \leq R_1$, $0 \leq R'_2 \leq R_2$, and $\alpha \in [0, 1]$, satisfying

$$R_f \geq I(Y; Y_1 | Y_{12}, U_1, X_1, W) + I(Y; Y_2 | Y_{12}, U_2, X_2, W) \\ + \max\{I(Y; Y_{12} | U_1, X_1, W), I(Y; Y_{12} | U_2, X_2, W)\}$$

$$R'_1 \leq I(U_1; Y_2, Y_{12} | U_2, X_2, W)$$

$$R'_2 \leq I(U_2; Y_1, Y_{12} | U_1, X_1, W)$$

$$R'_1 \leq I(U_1; Y | U_2, W) + \alpha I(W; Y)$$

$$R'_2 \leq I(U_2; Y | U_1, W) + \bar{\alpha} I(W; Y)$$

$$R'_1 + R'_2 \leq I(W, U_1, U_2; Y)$$

$$R_1 - R'_1 \leq I(X_1; Y | W, U_1, U_2, X_2)$$

$$R_2 - R'_2 \leq I(X_2; Y | W, U_1, U_2, X_1)$$

$$R_1 + R_2 - R'_1 - R'_2 \leq I(X_1, X_2; Y | W, U_1, U_2)$$

for some $p(w)p(u_1|w)p(u_2|w)p(x_1|u_1, w)p(x_2|u_2, w)p(y|x_1, x_2) \\ p(y_{12}|y, w)p(y_1|y_{1,2}, y, w)p(y_2|y_{1,2}, y, w)$.

Introduction

Channel and feedback models

Main result

► Coding scheme

► Achievable region

END

Achievable region (cont'd)

Theorem: For every memoryless finite alphabet MAC with feedback, \mathcal{R}_i is achievable.

Introduction

Channel and feedback models

Main result

- ▶ Coding scheme
- ▶ Achievable region

END

Achievable region (cont'd)

For perfect feedback, \mathcal{R}_i reduces to the Cover-Leung region, with transmission rates R'_1 and R'_2 .

$$R'_1 \leq I(X_1; Y|W)$$

$$R'_2 \leq I(X_2; Y|W)$$

$$R'_1 + R'_2 \leq I(X_1, X_2; Y)$$

for some $p(w)p(x_1|w)p(x_2|w)$

Obtained by substituting: $Y_{12} = Y_1 = Y_2 = Y$, $U_1 = X_1$, $U_2 = X_2$, and using the fact that Y is independent of W conditioned on X_1 and X_2 .

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Introduction

Channel and feedback models

Main result

▶ Coding scheme

▶ Achievable region

END

Future work

- ▶ Compute \mathcal{R}_i for specific models
- ▶ Extend to Bross-Lapidoth coding scheme.
- ▶ Variable rate feedback
- ▶ Outer bounds
- ▶ Separate feedback links

Thank You